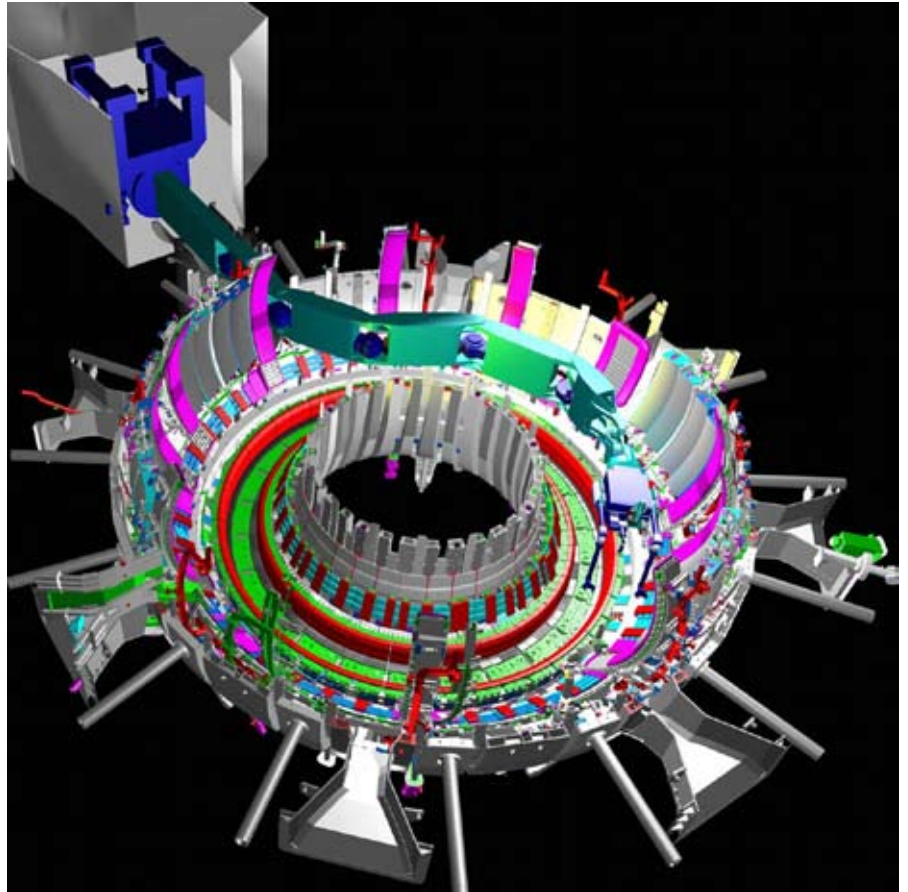


Tree C Technology B.V.

The success of REMOTE HANDLING will be a key factor in the safe exploitation of fusion energy. VR4Robots® offers the best combination of interactive visualization and remote handling technology to prepare and execute the demanding RH-tasks in ITER.

VR4Robots® enables you to define, visualize, animate, simulate and interact with robots and manipulators in a virtual world. The environment may include digital mock-up's based on 3D CAD data. Complex 'behaviors' of robots, cameras, animations, movement constraints and collision properties can be added to the environment to improve realism.

VR4Robots® is capable of handling the largest full scale mock-up facilities with the aim to prepare, demonstrate and execute remote maintenance, and to develop the remote maintenance operating procedures to facilitate development of components.



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